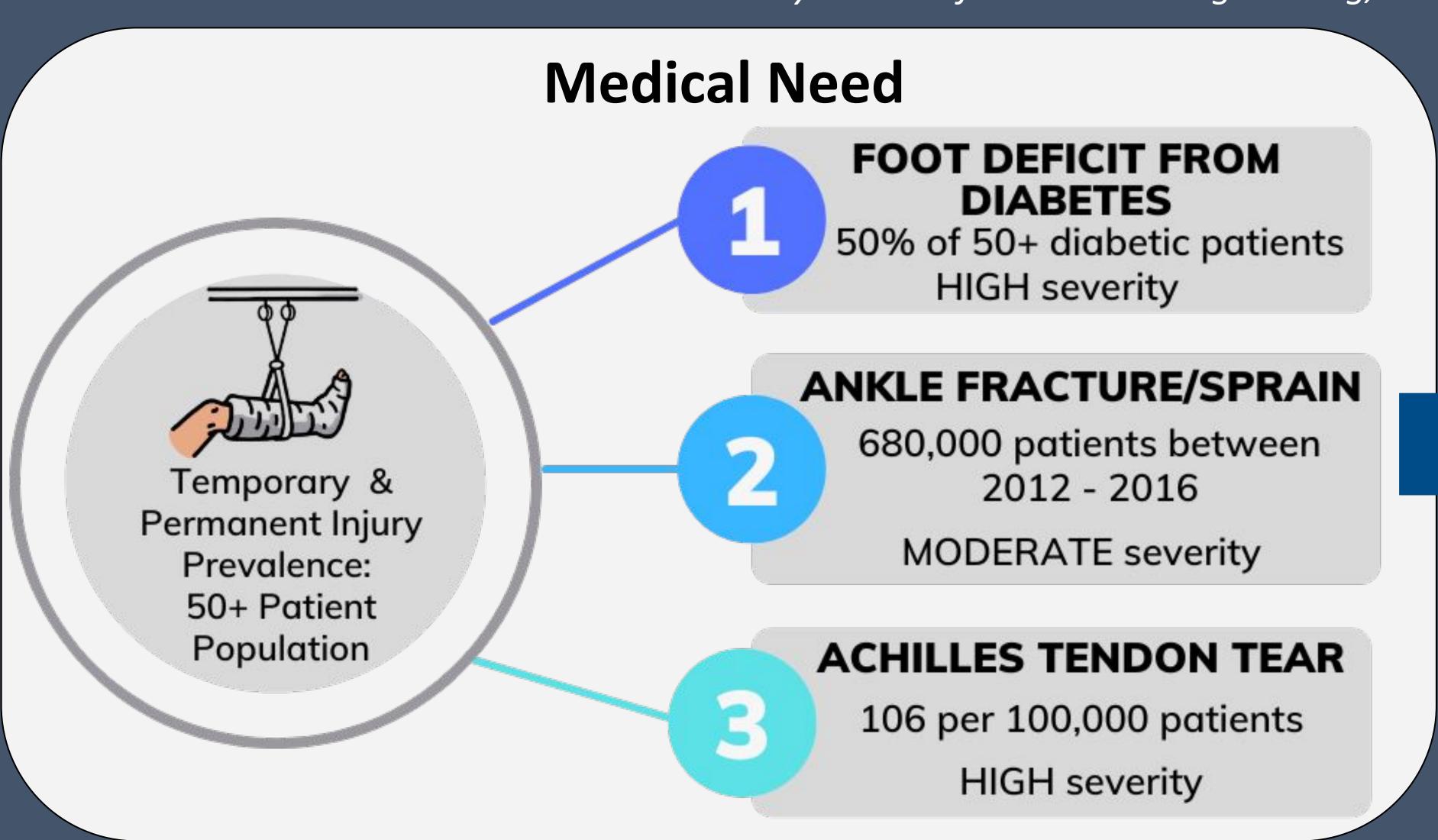
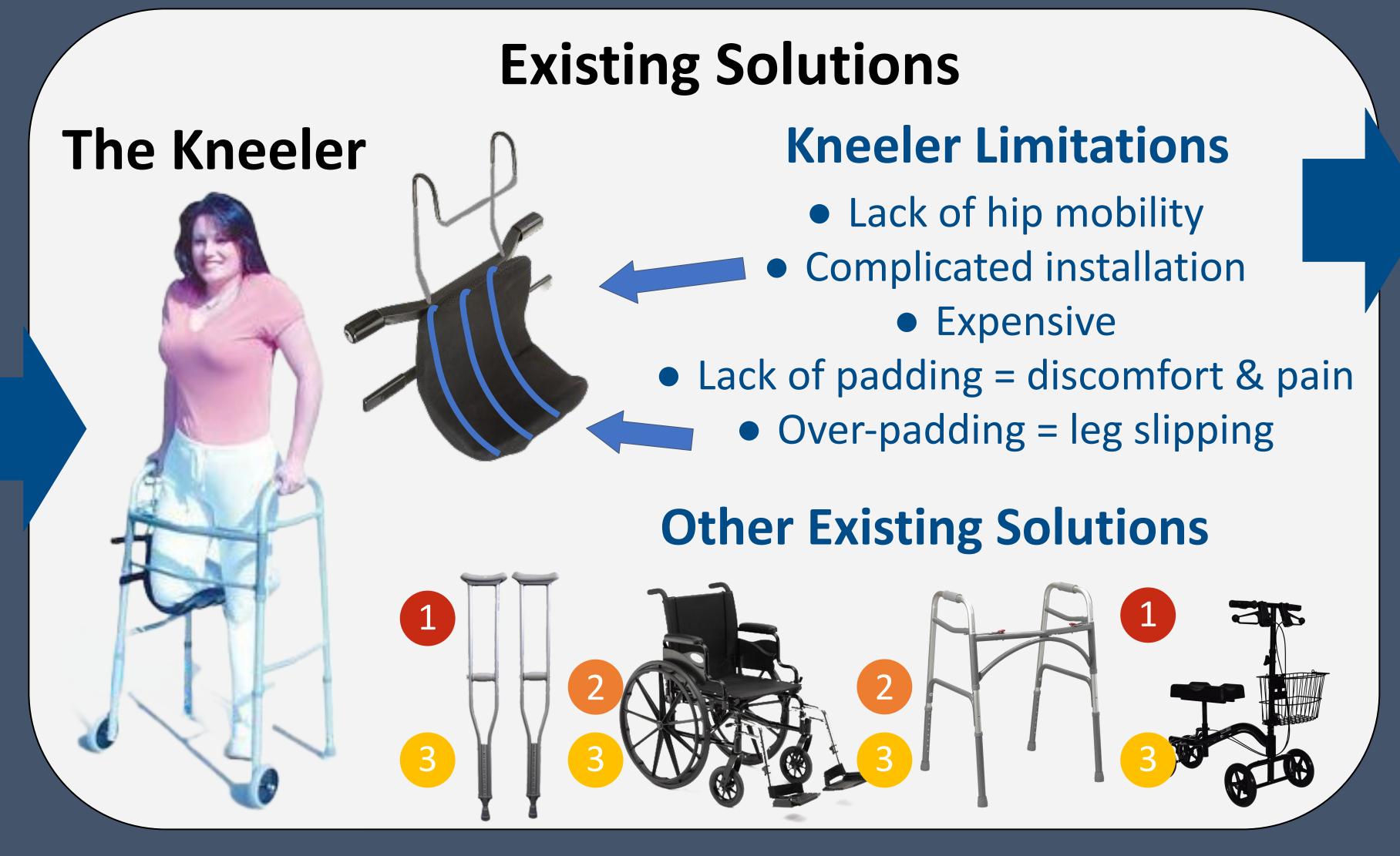


Dynamic Assistive Walking Device for Non-Weight-Bearing Injuries



Caitlyn Christopher¹, Sarah Cooney¹, Rory Klingensmith¹, Garrett White¹, Gregory Connors², Faith Kean², Tan Tran², Amged Eidelsafy², Ellie Wood², Dr. Adrian Shieh³, Dr. Kelly Heath³ Drexel University School of Biomedical Engineering, Science and Health Systems¹; Drexel College of Medicine²; University of Pennsylvania³





Objective

Assistive walking device that allows for:

- 1. Non-weight-bearing
- 2. Affordability 3. Controlled mobility

Improves on other existing solutions with:

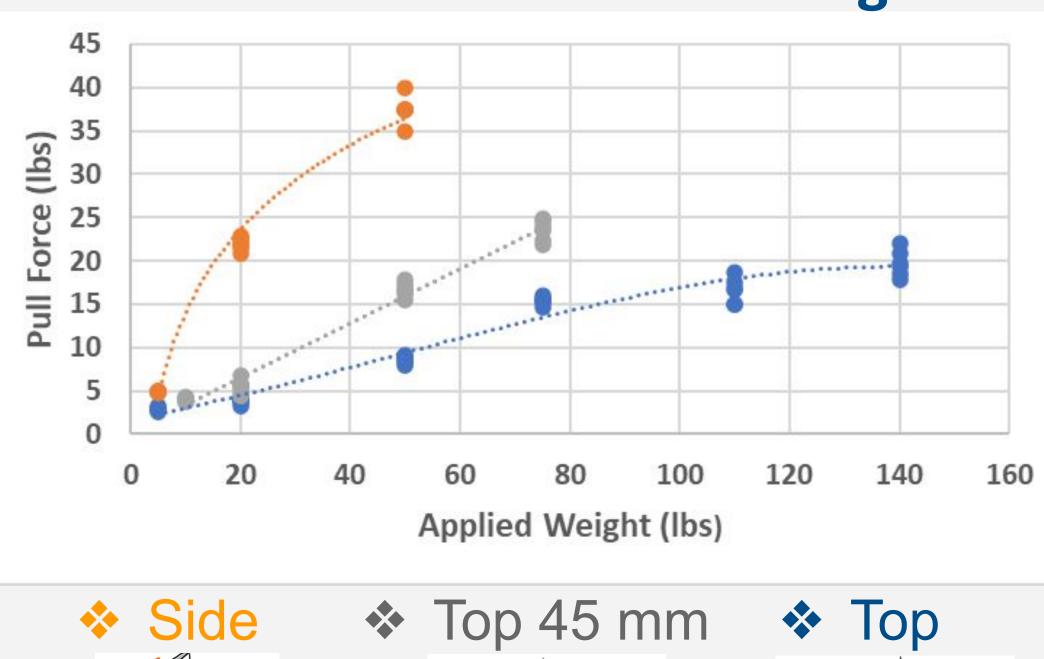
- Stability & control Mobility
 - Ease of use

Results

Component Testing

- Top orientation best suited for track roller
- Withstand 140 lbs (V1 will test to 230.4 lbs)
- Comparing efficacy of single & double rail for ROM & interference with healthy leg

Force to Pull Slider with Weights

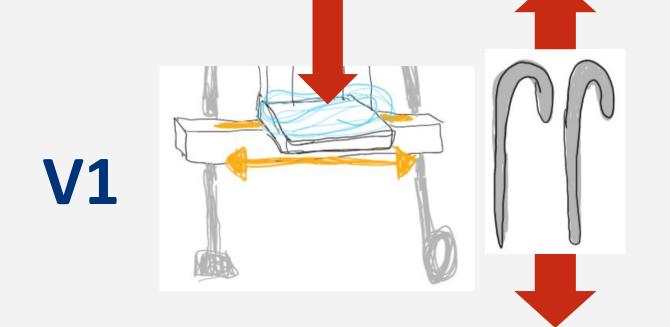


Results for V1, V2, V3 to be obtained

Component Testing:

- Weight applied on top or side?
- Single or Double Rail?

Verification Testing:



Compression and Tension

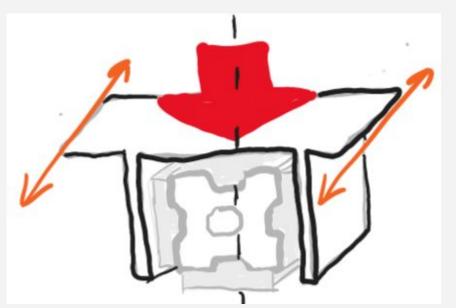


V3

Hip ROM Testing in Gait Lab

Hyperextension

Solution



Weight on Top



Single Rail or



Double Rail

Walker with **Embedded Slider** (Left leg use)



Features:

- Non-weight-bearing
- Holds patient population's weight
 - Dynamic for walking

Constraints

Size	Fits any walker's dimensions
Adjustable	Fits any patient's leg dimensions
Cost out-of -pocket	Max Price: \$230 (price of Kneeler)
Reversible	Either leg (right or left side of walker)
Safety	No falls/slips, boundaries for A-P motion
Ease of Use	Easy assembly, attachable to any walker

Requirements

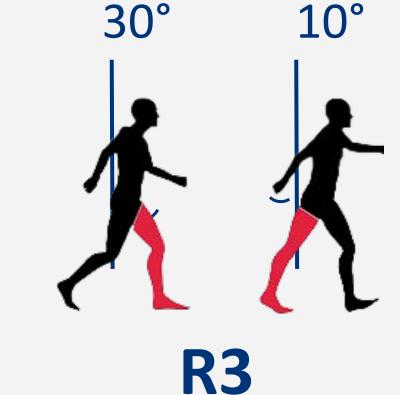


168 - 230.4 lbs





R2



<4,400 Pa Prevent pressure

ulcers

No significant difference in Hip ROM

Hold patient

- pop. weight
- Comfortable

Impact

- Prevent further injury aggravation & hip atrophy
 - Maintain mobility while walking
 - Ease financial burden (TBD)

Conclusion and Next Steps

- Further component testing to determine # of rails ___
 - Verification testing (V1, V2, V3)
 - Cost analysis

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